# A Noise-Adaptive Discriminant Function and Its Application to Blurred Machine-Printed Kanji Recognition

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Abstract—Accurate recognition of blurred images is a practical but hitherto mostly overlooked problem. In this paper, we quantify the level of noise in blurred images and propose a new modification of discriminant functions that adaps to the level of noise. Experimental results indicate that the proposed method actually enhances the existing statistical methods, and has impressive ability to recognize blurred image patterns.

Keywords—discriminant function, Mahalanobis distance, Bayes classifier, distribution of feature vectors, noise, blurred character recognition

#### I. INTRODUCTION

Significant achievements are made by statistical pattern recognition methods considering distribution of sample patterns in feature spaces [1], [2], [3]. In most conventional pattern recognition methods, the first step is extracting features from objects. These features are always expressed in the form of feature vectors. Then, the distribution of feature vectors is estimated for each category. Finally, an unknown input pattern is assigned to the category with the maximum probability.

Usually different types of noise may be present and no one can predict what kind of noise an unknown input pattern will carry. Because noise may change the appearance of a pattern, the feature vector extracted from a noisy image will be very different from that from a clean image. If the distribution is estimated with only noiseless samples, whereas the unknown input pattern is noisy, the recognition result is often unsatisfactory. On the other hand, if the distribution is estimated with noisy samples, there is no guarantee that the type of noise of an unknown input pattern is included in the training samples. For these reasons, selecting training samples is not the most essential element of constructing a dictionary for recognizing both clean and noisy patterns.

For noisy pattern recognition, many regularization methods of discriminant functions are proposed. These are done by adding a regularization term or by a noise injection to input signals [4], [5]. However, as it is known, distribution of feature vectors will change according to noise that occurs irregularly and accidentally. Therefore, how to quantify noise and formulate the relationship between noise and discriminant function is extremely important. In this paper, by introducing the concept of level of noise, a new modification method of existing discriminant functions is proposed, and a new discriminant function, called Adaptive Mahalanobis distance, is presented. In the proposed method, elements of feature vectors of an unknown input pattern are investigated whether they are with or without noise. Furthermore, distribution of feature vectors of each category is changed according to the noise detected from the unknown input pattern. It can quantify changes in noisy unknown samples and dynamically rectify the original distribution of categories according to the detected noise.

Although the research of Chinese character and Japanese character recognition has been continued [6], [7], [8] since Casey et al. opened up the field [9], methods for blurred character recognition still need to be developed. Compared to numerals and alphabet characters, the structure of Chinese characters is quite complex, and there is a large amount of structurally similar characters. Since Chinese characters have complex structures, if the character images are copied or transfered with facsimile, blurring can make the appearances quite different from the originals, and certainly feature vectors that absolutely depend on the

shapes of images will change according to noise. For these reasons, blurring is a serious problem in recognizing noisy Chinese characters.

In this paper, as a practical application of the Adaptive Mahalanobis distance, it is adopted to recognize blurred Kanji (Chinese characters used in Japan) images. With the experimental results, it is shown that the new discriminant function is extremely effective for blurred character recognition, and also has satisfactory performance on clean pattern recognition. All the results indicate that the proposed method supplements the existing statistical methods.

#### II. RELATED WORK

Some methods for recognizing poor quality characters have been proposed. Hobby et al. [10] have developed a method to enhance degraded document images by finding and averaging bitmaps of the same kind of symbols. It improves the display appearance and recognition accuracy. Chou et al. have proposed a flexible matching method between template images and unknown character images [11]. A vector field, called character deformation field, is used to represent deformation. Rodríguez et al. have exploited a two-stage classifier [12]. First, a multi-font classifier is applied. Then, a specialized classifier rerecognizes the ambiguous patterns using the patterns whose certainty of correct classification is high.

With the widespread use of digital cameras, some studies on recognizing poor quality characters that exist in the images taken by digital cameras have been done [13], [14], [15]. Sawa et al. use the Gaussian Laplacian filter to emphasize images [13]. Then segmentation and recognition of characters are accomplished with dynamic programming. The moving subtraction method has been proposed by Kosai et al. [14]. It uses plural images by swinging a camera vertically and horizontally, to supplement the bad influence caused by the lowness of resolution. The method developed by Sawaki et al. prepares a multipledictionary to deal with the images under any conditions [15]. The environmental condition of an image is estimated, and a relevant dictionary reflecting the condition is used for recognition.

All these methods focus on how to construct an optimal reference pattern or a dictionary from training samples. However, it is more important to detect noise and to rectify discriminant function according to the noise for blurred image recognition. Moreover, some of these methods deal with multiple-valued images. However, thickness of character images that are copied or transfered with facsimile is mostly binarized to white or black, with no intermediate thickness. Therefore, these methods are not proper for this case.

# III. DISCRIMINANT FUNCTION REFLECTING CHANGE IN DISTRIBUTION

During an observation process, it is very difficult to avoid the occurrence of noise. Some kinds of noise such as noise that occurs in character images is neither uniform nor continuous, and it often only appears on certain parts of an object. The features of an object are expressed as a feature vector in most pattern recognition methods. As a result, noise will only appear on some elements of a feature vector, whereas the other elements will keep the essential values. In this case, the standard deviation of the elements with noise will become larger corresponding to degree of noise.

Because noise happens irregularly and accidentally, it is impossible to make a complete dictionary that can include all kinds of noise. Even if it will be possible, that dictionary might not be valid for clean images. The main purpose of this study is to quantify the relationship between noise and distribution of category and to rectify distribution dynamically according to degree of noise. To quantify the relationship between degree of noise and change in distribution, an appropriate way is to calculate the ratio of standard deviation of elements with b degrees of noise to those of noiseless elements. The ratio can be denoted as

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Fig. 1. Change in distribution. (a) Original distribution, (b) Changed distribution.

 $r_b$ . Obviously, the ratio of standard deviation takes the role of intermediation between noise and distribution of category. From this point of view, a new discriminant function that reflects the change in distribution can be proposed by considering the ratio of standard deviations.

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Here, the Mahalanobis distance and the Bayes classifier of multivariate normal distribution are considered. Let  $\mu$  and  $\Sigma$  be the mean vector and the  $n \times n$  covariance matrix, respectively. The squared Mahalanobis distance from  $\mu$  to x is defined as

$$d^{2} = (\boldsymbol{x} - \boldsymbol{\mu})^{t} \Sigma^{-1} (\boldsymbol{x} - \boldsymbol{\mu}).$$
(1)

The squared Mahalanobis distance is abbreviated as the Mahalanobis distance below. The discriminant function for the Bayes classifier with equal prior probabilities of all categories is defined as

$$g = (\boldsymbol{x} - \boldsymbol{\mu})^{t} \Sigma^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) + \log |\Sigma|.$$
(2)

For simplicity, the case of two-dimensional normal distribution is discussed first. As shown in Fig. 1(a),  $e_1$  and  $e_2$  are the axes of the original coordinate. Let  $\phi_1$  be the eigenvector that corresponds to the first principal component. When b degrees of noise is added to  $e_1$ -element while  $e_2$ -element is noiseless, it is observed that only the standard deviation of  $e_1$ -element becomes  $r_b$  times larger. Then the change in the distribution can be illustrated as Fig. 1(b).

Let b(j) be the degree of noise added to the *j*th element of *n*-dimensional feature vector  $\boldsymbol{x}$ . Suppose that the mean vector is not changed and the standard deviation of *j*th element of  $\boldsymbol{x}$  becomes  $r_{b(j)}$  times larger where  $r_{b(j)}$  is determined depending on the value b(j). For noiseless elements, say  $j, r_{b(j)} = 1$ .

Let  $x_i$  be a noiseless sample, and  $y_i$  be a sample with noise (i = 1, 2, ..., N). The observation on the change in deviation by noise may be described as the following. Let  $x_i = \mu + x'_i$ , and  $y_i$  be the corresponding noisy data such that  $y_i = \mu + y'_i$ . If the *j*th element of  $y'_i$ is changed from  $x'_i$  as  $y'_{ij} = r_{b(j)}x'_{ij}$ , then the standard deviation  $\hat{\sigma}_j$ of  $y'_{ij}$  is  $r_{b(j)}$  times larger than that of  $x'_{ij}$ . If a diagonal matrix *K* is defined as

$$K = \begin{bmatrix} r_{b(1)} & & 0 \\ & r_{b(2)} & & \\ & & \ddots & \\ 0 & & & r_{b(n)} \end{bmatrix},$$
(3)

which is called *revision matrix*, then,  $y'_i (= y_i - \mu)$  can be written as  $y'_i = K x'_i$ .

Using the above equations, the covariance matrix of noisy samples  $\hat{\Sigma}$  is calculated as,

$$\hat{\Sigma} = \frac{1}{N-1} \sum_{i=1}^{N} (y_i - \mu) (y_i - \mu)^t$$

$$= \frac{1}{N-1} \sum_{i=1}^{N} (K x_i') (K x_i')^t$$

$$= \frac{1}{N-1} \sum_{i=1}^{N} K (x_i - \mu) (x_i - \mu)^t K^t$$

$$= K \Sigma K.$$
(4)

Note that  $K = K^t$ . In order to reflect the change in distribution, the following discriminant functions that include the revision matrix K is proposed.

$$\hat{d}^2 = (\boldsymbol{x} - \boldsymbol{\mu})^t \hat{\Sigma}^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) = (K^{-1} (\boldsymbol{x} - \boldsymbol{\mu}))^t \Sigma^{-1} (K^{-1} (\boldsymbol{x} - \boldsymbol{\mu})),$$
 (5)

$$\hat{g} = (x - \mu)^{t} \hat{\Sigma}^{-1} (x - \mu) + \log |\hat{\Sigma}| 
= (K^{-1} (x - \mu))^{t} \Sigma^{-1} (K^{-1} (x - \mu)) 
+ \log |\Sigma| + 2 \log |K|.$$
(6)

Here, x is a noisy observation. Eqs. (5) and (6) are called *Adaptive Mahalanobis distance* and *Adaptive Bayes classifier*.

## IV. APPLICATION TO BLURRED KANJI RECOGNITION

Although noisy Kanji recognition is very necessary and important in a practical character recognition system, there have been few attempts that give expressive performance. In this paper, a new discriminant function for noisy pattern recognition is proposed. As one of its practical applications, Eq.(5) is rectified to fit the characteristic of character images. Recognition experiments are performed with blurred machine-printed Kanji images to confirm the effectiveness of the proposed method.

The Directional Element Feature [16] is used as the feature vector here. The effectiveness of this feature is shown with clean machineprinted Kanji images [16]. It is calculated as follows. First, input image is normalized to  $64 \times 64$  dots and thinned. Then it is divided into 49 areas of  $16 \times 16$  dots where each area overlaps 8 dots of the adjacent area. For each area, a four-dimensional vector is defined to represent the quantities of the four orientations: vertical, horizontal, and two oblique lines slanted at  $\pm 45^{\circ}$ . Thus the total vector for one character has 196 (=  $49 \times 4$ ) dimensions.

#### A. Discriminant Function

According to the simulation results [17], [18], the Adaptive Mahalanobis distance is superior to the Adaptive Bayes classifier in the case that noise is terrible, i.e., the value of b(j) is large. Therefore only the Mahalanobis distance is investigated below.

In the case of recognizing character patterns, it is known that the Mahalanobis distance has disadvantages. One big disadvantage is caused by small number of samples [19], [20], [21]. To decrease this influence, many regularization methods of discriminant functions are proposed [4], [5]. One typical method is to add a regularization term to  $\Sigma$ . In order to examine this kind of method, Eq. (1) is modified as follows.

$$d_R^2 = (\boldsymbol{x} - \boldsymbol{\mu})^t (\boldsymbol{\Sigma} + \alpha I)^{-1} (\boldsymbol{x} - \boldsymbol{\mu}).$$
<sup>(7)</sup>

Here, I is an identity matrix and  $\alpha$  is a small positive constant. In the following experiments,  $\alpha = 0.1$ . In this paper, Eq. (7) is called regularized Mahalanobis distance, or RMD.

Another big problem of the Mahalanobis distance is the expensive computation cost, especially when it is used for Kanji recognition that uses usually very high dimensional feature vectors. To reduce the computation cost, various modifications of the Mahalanobis distance are proposed. Three typical methods are the Quasi-Mahalanobis distance [22] (QMD), the Modified Mahalanobis distance [23] (MMD), and the Simplified Mahalanobis distance [24] (SMD). The statistical properties of the SMD is most similar to the Mahalanobis distance among the three functions, and its effectiveness has been shown [24] with ETL9B [25], which is the largest handwritten character database in Japan.

In order to explain the SMD, Eq. (1) is rewritten as

 $\alpha$ 

$$d^{2} = \sum_{i=1}^{n} \frac{1}{\lambda_{i}} ((\boldsymbol{x} - \boldsymbol{\mu})^{t} \boldsymbol{\phi}_{i})^{2}.$$
 (8)

Here,  $\lambda_i$  is the *i*th eigenvalue of  $\Sigma$  sorted by descending order, and  $\phi_i$  is the eigenvector that corresponds to  $\lambda_i$ . The SMD replaces  $\lambda_i (i > m)$  in Eq. (8) with the mean value  $\alpha_m$  of  $\lambda_i$  (i = m + 1, ..., n), and it is written as

$$d_{S}^{2} = \sum_{i=1}^{m} \frac{1}{\lambda_{i}} ((\boldsymbol{x} - \boldsymbol{\mu})^{t} \boldsymbol{\phi}_{i})^{2} + \frac{1}{\alpha_{m}} \sum_{i=m+1}^{n} ((\boldsymbol{x} - \boldsymbol{\mu})^{t} \boldsymbol{\phi}_{i})^{2}$$
$$= \sum_{i=1}^{m} \frac{1}{\beta_{i}} ((\boldsymbol{x} - \boldsymbol{\mu})^{t} \boldsymbol{\phi}_{i})^{2} + \frac{1}{\alpha_{m}} \|\boldsymbol{x} - \boldsymbol{\mu}\|^{2},$$
(9)

where

$$_{m} = \frac{\mathrm{tr}\Sigma - \sum_{i=1}^{m} \lambda_{i}}{n - m}, \qquad (10)$$

$$\frac{1}{\beta_i} = \frac{1}{\lambda_i} - \frac{1}{\alpha_m}.$$
 (11)

The revision matrix K proposed in Section III can be introduced to many discriminant functions. In this paper, to investigate the effectiveness of the revision matrix K to noisy pattern recognition, K is introduced to RMD and SMD, and the expressions are expressed as

$$\hat{d}_{R}^{2} = (K^{-1}(\boldsymbol{x} - \boldsymbol{\mu}))^{t} (\Sigma + \alpha I)^{-1} (K^{-1}(\boldsymbol{x} - \boldsymbol{\mu})), \quad (12)$$

$$\hat{d}_{S}^{2} = \sum_{i=1}^{N} \frac{1}{\beta_{i}} ((\boldsymbol{x} - \boldsymbol{\mu})^{t} K^{-1} \boldsymbol{\phi}_{i})^{2} + \frac{1}{\alpha_{m}} \|K^{-1} (\boldsymbol{x} - \boldsymbol{\mu})\|^{2}.$$
(13)

Eq. (12) that modifies the RMD by the addition of the revision matrix K, is called Adaptive RMD. Similarly, Eq. (13) is called Adaptive SMD. Note that the computational cost of the Adaptive RMD is  $O(n^2)$ , and it is much more expensive than that of the Adaptive SMD which is O(nm) for  $m \ll n$ .

#### B. Degree of Blur

*B.1. Definition.* In order to quantify level of noise, the concept of *degree of blur* is introduced. Degree of blur is defined for each area of a character image, and it is calculated in the thinning process. Thinning is a repeating process of erasing a black pixel from boundaries of black pixels of a character image. By scanning neighbor pixels around each black pixel, stroke width of a character image is finally erased to one-pixel [26], [27]. Figs. 2(a) and 2(e) are examples of a normalized blurred image and a clean image. The erasing process of these images are shown by Figs. 2(b)~2(d) and Figs. 2(f)~2(h), respectively. In order to get a completely thinned image of Fig. 2(d), fourteen times of repetitions are needed to erase pixels on boundaries, while Fig. 2(h) requires only four repetitions.

If the repetition times in the thinning process is limited to the number that a clean image is completely thinned, obviously it will not be enough for a blurred image. To decide the optimum number of times for thinning a clean image, pre-experiments are carried out with 2,964 different clean Kanji images<sup>1</sup> scanned at 400 dots per inch. The size of each image is  $128 \times 128$ . For different numbers of repetition times, the number of completely thinned character images is counted. Two mainly used fonts, Mincho and Gothic, are examined here. The amounts and percentages of completely thinned character images are shown in Table I. The tendencies of two fonts are similar, and it has shown that over 96% of the character images are completely thinned after six times erased. Obviously, six times is not the optimum number for any font. The optimum number depends on font and complexity of characters. Fortunately, no matter what kind of font is used, for each kind of font, the maximum width of line segments that are used for constructing a character is usually fixed. Therefore, calculating an optimum number of a certain kind of font is not a difficult task. In the above case, a Kanji image can be regarded as a blurred one if any line width is more than one-pixel after being thinned six times.

Since noise in character images is neither uniform nor continuous, an image usually includes both clean parts and blurred parts. It is thought to be more feasible to examine blurred parts of image area by area. Here, for every one of the 49 areas, the number of black pixels that are not located at boundaries is counted, and the quantized value of  $\lfloor (\text{Number of black pixels})/M \rfloor$  is defined as *degree of blur*. Since the largest number of black pixels in one area is  $16 \times 16 = 256$  pixels, in order to represent the degree as a single figure, in the experiments, M = 32. The value of degree of blur is either zero or a positive integer not greater than eight. Hence, the greater value of degree means the blur in that area is more severe. Fig. 3(a) shows the contour image (pixels that are located at boundaries) of Fig. 2(c), and Fig. 3(b) gives the detected blurred region.

*B.2. Characteristics.* If a character image has been damaged by photocopying or facsimile, the appearance of the image is often blurred. Degree of blur is defined to describe the state of each area of an image. In order to quantize the change in the feature distribution of a category, it is necessary to investigate how much the standard deviation of each element of feature vector changes according to the degree of blur. For this purpose, 2,965 kinds of Kanji of ten sizes (from 6 point to 22 point) are used to carry out a pre-experiment. Small font character images are

<sup>&</sup>lt;sup>1</sup>The number of Kanji that are included in the first class of Japanese Industrial Standard (JIS) is 2,965. Among these characters, '\_\_,' which seems to have a special structure, is not used.



Fig. 2. Thinning process of (A) blurred image and (B) clean image. (a) Normalized image, (b) 3 times erased, (c) 6 times erased, (d) completely thinned. (e) Normalized image, (f) 1 time erased, (g) 2 times erased, (h) completely thinned.



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Fig. 3. Detection of Blur. (a) Contour image, (b) Detected blurred region.

TABLE I THE NUMBER OF COMPLETELY THINNED CHARACTER IMAGES AT EACH NUMBER OF TIMES OF THINNING.

Number of Times of Thinning	Mincho	Gothic		
3	8 (0.3%)	0 (0.0%)		
4	946 (31.9%)	605 (20.4%)		
5	2346 (79.1%)	2420 (81.6%)		
6	2869 (96.7%)	2920 (98.5%)		
7	2961 (99.8%)	2963 (99.9%)		
8	2964 (100.0%)	2964 (100.0%)		

damaged easily. All these sample patterns are scanned at 400dpi by an optical image scanner and are transformed to feature vectors.

Let  $x_{ij}^k$  be the *i*th element of a feature vector of *j*th sample pattern of category k, and  $b_{ij}^k$  be the degree of blur of  $x_{ij}^k$ . First, the mean value  $\bar{x}_i^k$  and the standard deviation  $\sigma_i^k$  are calculated from the areas whose degree of blur is zero. That is,

$$\bar{x}_{i}^{k} = \frac{1}{|J_{i}^{k}|} \sum_{j \in J_{i}^{k}} x_{ij}^{k}, \qquad (14)$$

$$\sigma_i^k = \sqrt{\frac{1}{|J_i^k|} \sum_{j \in J_i^k} (x_{ij}^k - \bar{x}_i^k)^2},$$
(15)

TABLE II Relationship between degree of blur and ratio of standard deviations.

Ratio
1.0
5.0
8.3
10.0
12.5
20.0

where the set

$$J_i^k = \left\{ j | b_{ij}^k = 0 \right\}, \tag{16}$$

and  $|J_i^k|$  is the number of elements in the set  $J_i^k$ . Each value  $x_{ij}^k$  is normalized as

$$\hat{x}_{ij}^k = \frac{x_{ij}^k - \bar{x}_i^k}{\sigma_i^k}$$

Then  $r_b$  ( $0 \le b \le 8$ ) is determined as follows.

$$r_{b} = \begin{cases} 1 & \text{if } b = 0\\ \sqrt{\frac{1}{|D_{b}|} \sum_{(i,j,k) \in D_{b}} (\hat{x}_{ij}^{k} - m_{b})^{2}} & \text{otherwise,} \end{cases}$$
(17)

where

$$D_b = \{(i, j, k) | b_{ij}^k = b\},$$
(18)

$$m_b = \frac{1}{|D_b|} \sum_{(i,j,k) \in D_b} \hat{x}_{ij}^k.$$
 (19)

It means the ratio  $r_b$  of standard deviation of the areas with *b* degrees of blur to the areas with zero degree of blur is calculated.

The results are summarized in Table II. The value of the ratio of standard deviation  $r_b$  increases as the value b of the degree of blur becomes larger. This verifies that the distribution of the feature vectors is changed by blur, and the amount of change in distribution can be described by the degree of blur. Adaptive SMD

7.2%



Fig. 4. Data for experiments. (a) 8 point, copied with thin mode, (b) 6 point, copied with thick mode.
TABLE III

EXPERIMENTAL RESULTS.						
Mathad	Thin mode			Thick mode		
Method	6pt	7pt	8pt	6pt	7pt	8pt
RMD	4.3%	0.9%	0.1%	16.7%	8.3%	0.8%
Adaptive RMD	3.4%	0.7%	0.1%	8.5%	4.2%	0.7%
SMD	11.4%	2.5%	0.3%	28.6%	15.2%	1.7%

0.3%

12.8%

5.5%

1.0%

1.5%

#### C. Experiments

For the experiments, 2,965 kinds of Kanji that are commonly used in Japan are adopted. Machine-printed single font characters of ten sizes (from 6 point to 22 point) are prepared as training data. All these sample patterns are scanned at 400 dots per inch by an optical image scanner and are transformed to feature vectors. Test data includes three sizes of printed characters (6, 7 and 8 points) photocopied with two mechanically controlled modes (thin mode and thick mode). The appearances of the copied images are very blurred, especially the ones copied with thick mode. Examples of sample character images are displayed in Fig. 4. In the figure, (a) shows 8 point characters copied with thin mode, while (b) shows 6 point characters copied with thick mode. The qualities of these sets are quite different.

As discriminant functions, RMD, Adaptive RMD, SMD and Adaptive SMD are used. The value of m in Eq. (13) is five. The revision matrix K based on the degree of blur in each area is estimated for each individual unknown character.

Experimental results (error rates) are shown in Table III. The error rates of RMD are smaller than that of SMD. However, computational cost of the RMD is about forty times larger than that of the SMD. In every case of our experiments, the error rates of the Adaptive RMD and the Adaptive SMD are smaller (or has no change) compared with the results of the RMD and the SMD, respectively. Most of conventional methods have focused on how to construct an optimum dictionary for noisy image recognition, the error rate unfortunately tends to increase if recognition objects are clean. Here, in the experiments of recognizing the comparatively clean character images, such as 7 and 8 points copied with thin mode, the ability of the Adaptive discriminant functions are as good as, or even better than the original ones which give fine performance on clean character recognition. Furthermore, the recognition results of the poor quality images, for instance, 6 and 7 points copied with thick mode, reveal that the Adaptive discriminant functions can decrease the error rates to about half compared to the original ones. All of these results confirm that the proposed modification method can inspect the state of an unknown input image, and adapt the discriminant functions. The experimental results show that the Adaptive discriminant functions can deal with both clean and noisy patterns simultaneously and effectively.

Table IV shows some examples that are correctly recognized by the Adaptive SMD, while they are missed by the original SMD. Original

images, correct answers, and candidates selected by these two discriminant functions are displayed in the table. Apparently, each combination of answer and candidate of the original SMD are quite similar, and the distinctive parts among these similar characters are exactly the blurred parts. In the case of column (a), because the right part of the image is clean, the right parts of both candidates of the Adaptive SMD and the SMD have the same structure. However, since the left part of the image is blurred, the SMD selects a similar but incorrect candidate. For the Adaptive SMD, the information of the blurred part, especially the relatively clean area in the blurred part like the upper-left area of the image, helped to achieve success in recognition process.

Our experiments have tested only one font. However, if the data is a multi-font document, the problem will be troublesome. How to find an optimum number of times of thinning for a multi-font document or characters with different structural complexities is an arduous task for improving our method. Moreover, there are some peculiarity of Kanji that should be concerned. For example, for some kinds of designs of Kanji, such as *Mincho* font, the width of vertical stroke is much wider than the width of horizontal stroke. If blurring occurs between two vertical strokes, the noise will be easily detected by our method. However, if the space between two horizontal strokes is blurred, the noise is almost impossible to be found, since the width of the two joint horizontal strokes may be smaller than the width of one vertical stroke.

#### V. CONCLUSIONS

For most statistical methods of pattern recognition, achieving the exact expression of distribution of feature vectors is the first step of accurate recognition. However, in the case that noise is included in an image, the feature vector will be quite different from that of a clean

TABLE IV							
EXAMPLES	OF IMAGES	THAT AR	E CORRECTLY	RECOGNIZED	BY THE A	DAPTIVE	SMD

		(a)	(b)	(c)
Image		台	Ħ	疱
Answer	飴	闇	憶	
Candidate	Adaptive SMD	飴	闇	憶
	SMD	胎	簡	撹

image. Since noise occurs irregularly and accidentally, it is difficult to create a dictionary that can cope with all kinds of noise, regardless of using numerous kinds of noisy training patterns.

In this paper, by analyzing the characteristics of noise, a new modification of discriminant functions for recognizing noisy patterns has been presented. Blurred Kanji recognition is adopted to examine the usefulness of the proposed discriminant function in solving practical problems. In order to quantify the relationship between noise and change in distribution, the ratio of the standard deviation of the elements with a certain degree of blur to noiseless elements is introduced. Then a revision matrix is constructed using these ratios. By introducing the revision matrix to the Mahalanobis distance, Adaptive Mahalanobis distance has been proposed. Since the Adaptive Mahalanobis distance always considers the information from an unknown pattern, and can adapt corresponding to the condition of individual patterns, it is a more suitable discriminant function in coping with various quality patterns simultaneously. The effectiveness of this discriminant function is confirmed by the experimental results of blurred character recognition.

The proposed discriminant function can be used for other practical noisy pattern recognition such as speech recognition and face recognition provided that a way can be found to calculate the revision matrix. Also, the revision matrix can be easily incorporated into other discriminant functions. To make our model effective for multi-font document and other kinds of noise is the future work.

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